
Incremental Object Model Learning from Multimodal Human-Robot Interactions

SUPPLEMENTARY MATERIAL

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Additional experimental results

This supplementary material includes more detailed results from the experimentation performed to compare the proposed incremental learning approach with different variations and baselines (both incremental and offline), using *Manually cropped patches* (typically clean and less cluttered) in Table 1 and *Automatically segmented patches* in Table 2.

Table 1: Object recognition accuracy (22 Objects), *Manually Cropped patches*

(a) Incremental k-NN									
	# of users processed to build the model								
	1	2	3	4	5	6	7	8	9
	20-cluster limit per class								
<i>BoW_{ORB}</i>	7,6	7,2	8,0	8,3	9,0	9,6	10,4	10,3	11,3
<i>HC_{RGB}</i>	10,7	17,9	23,1	26,0	28,0	29,6	30,8	31,1	31,4
<i>SIFT</i>	6,1	5,5	5,2	5,4	6,4	8,5	8,9	7,3	6,8
<i>DenseNet₄</i>	9,92	12,28	13,90	15,16	18,28	20,04	20,78	21,62	21,17
	No cluster limit per class (ALL)								
<i>BoW_{ORB}</i>	7,6	7,2	8,0	8,4	9,1	9,7	10,8	11,3	11,8
<i>HC_{RGB}</i>	10,7	17,9	23,1	25,8	27,6	28,4	29,2	30,3	30,2
<i>SIFT</i>	6,1	5,5	5,2	5,5	6,0	6,9	7,2	7,3	7,3
<i>DenseNet₄</i>	9,92	12,28	14,30	15,16	19,00	19,34	20,29	22,82	24,14
(b) Offline baselines									
k-NN+ <i>BoW_{ORB}</i>									11,8
k-NN+ <i>HC_{RGB}</i>									30,2
k-NN+ <i>SIFT</i>									7,3
k-NN+ <i>FC7</i>									2,2
<i>SVM</i> + <i>HC_{RGB}</i> [2]									34,8
<i>Inception-based</i>									59,3

Table 2: Object recognition results using *Automatic Patches* (22 classes, random chance 4.45).

	Accuracy	STD (10-fold cross val.)
Previous Work (offline) [2]:		
<i>SVM</i> + HC_{RGB} (Automatic patches)	7.95	6.6
<i>SVM</i> + HC_{RGB} (Automatic Inspected patches)	11.45	10.53
Other offline baselines:		
Offline k-NN (HC_{RGB})	13.4	6.56
Inception-based	17.5	6.51
Incremental:		
Incremental-50 (HC_{RGB})*	9.0	6.35
Incremental-100 (HC_{RGB})**	13.2	6.30
Incremental-50 (<i>DenseNet</i> ₄)*	5.55	3.98
Incremental-100 (<i>DenseNet</i> ₄)**	5.64	3.53

* Performance after 50% of data processed by the incremental system

** Performance after 100% of data processed by the incremental system